



Hybrid Lyot Coronagraph for WFIRST: High Contrast Testbed Demonstration in Flight-Like Low Flux Environment

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Jet Propulsion Laboratory
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Companion paper: 10698-94: [WFIRST Low Order Wavefront Sensing and Control Testbed Performance Under Flight Like Photon Flux](#) by Fang Shi, et al

The decision to implement the WFIRST mission will not be finalized until NASA's completion of the National Environmental Policy Act (NEPA) process. This document is being made available for information purposes only.

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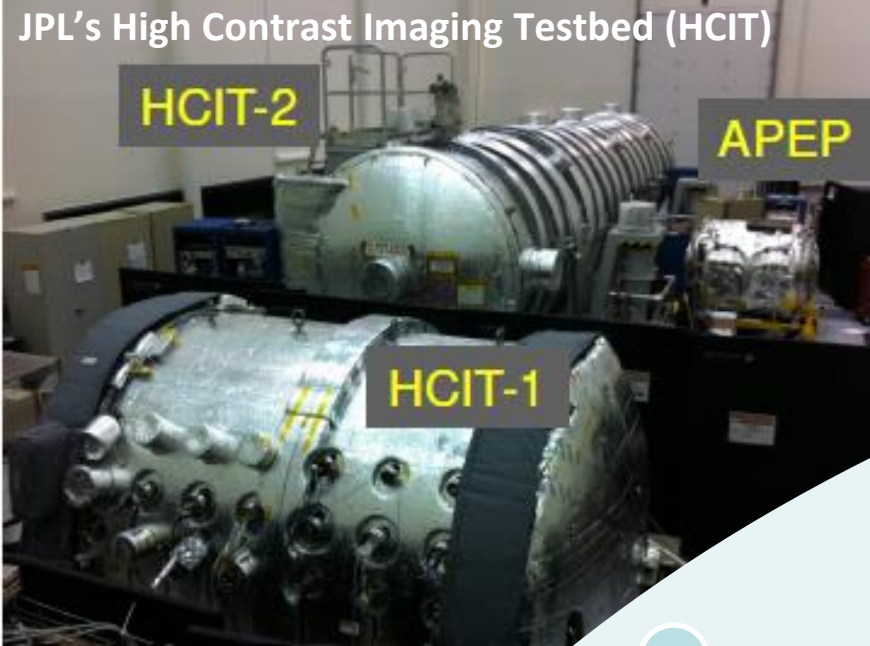


Outline



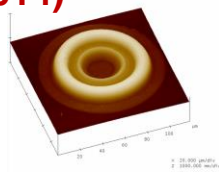
- **Testbed activity overview for WFIRST**
- **Flight flux estimation for WFIRST**
- **E-Field estimation error in low flux environment**
- **Test setup & Result**
- **Summary & Future works**

Brief History of WFIRST HLC Testbed Activity

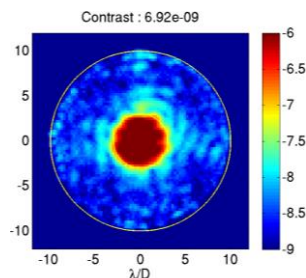


Coronagraph is added to WFIRST mission. (2013)

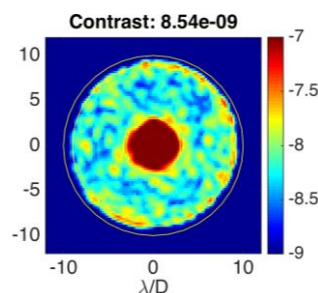
Hybrid Lyot occulting mask fabricated and characterized (2014)



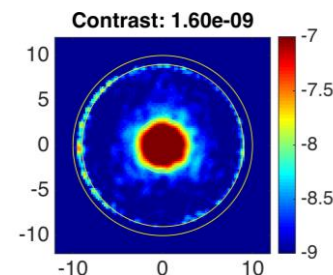
Narrowband 360° HLC contrast demonstrated with WFIRST pupil and 2 DMs (2015, 6.92×10^{-9} @ 550nm, 3-9 λ/D in HCIT2)



Broadband (10%) HLC contrast demonstrated (2015, 8.54×10^{-9} @ 550nm, 3-9 λ/D in HCIT2)



Broadband (10%) HLC contrast demonstrated in dynamic testbed & model validation (2017, 1.60×10^{-9} @ 550nm, 3-9 λ/D in HCIT1)





Flight vs. Testbed



	WFIRST Flight	Testbed
Star Flux	Low	High
Science Detector	EMCCD	Commercial CMOS
Computation Resource	Low	High
OTA	Telescope OTA	Simulator
LOWFS	Correct 10 Zernike modes (ZM2-ZM11)	Correct 3 Zernike modes (ZM2-ZM4)

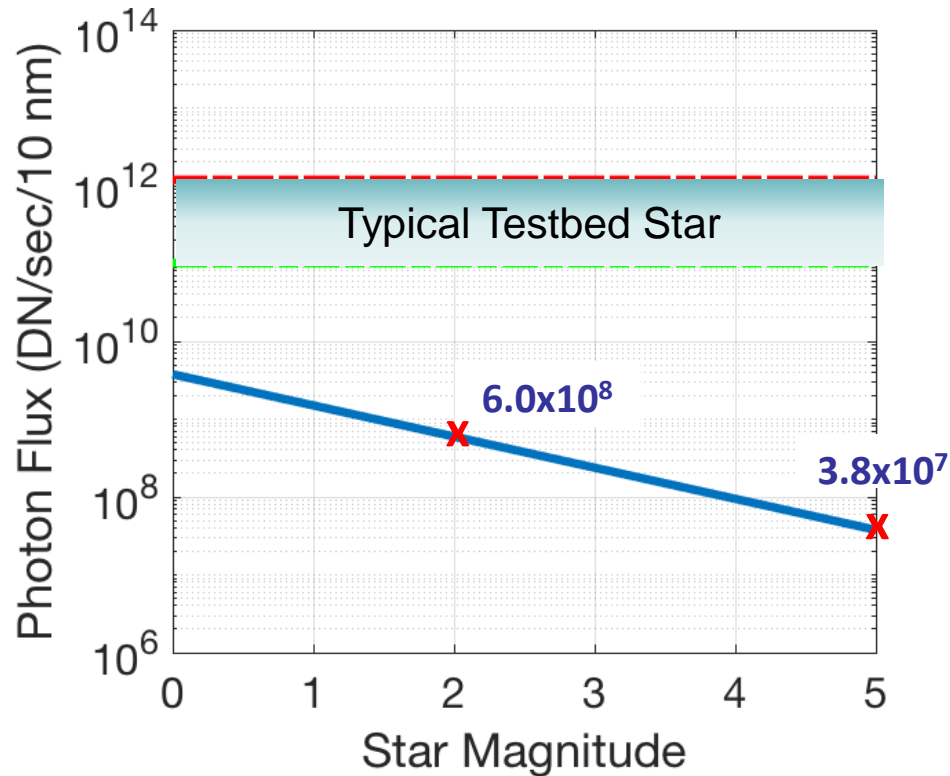


Motivation

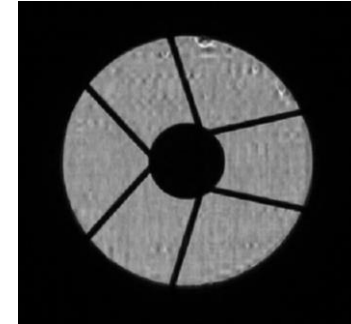


Can we make & maintain a dark hole with
WFIRST flight-like low flux condition?

WFIRST Flux Estimation



Testbed Pupil image
where photon flux is counted



- Assumptions for WFIRST Flux Estimation
 - G0V type star
 - QE=92.9% (Flight CBE@575 nm)
 - Loss = 0.566×0.9 (flight CBE, Req=0.4)

- WFIRST Requirement:**
 - Reference Star = V2 & Target Star = V5
- Testbed star is 200~2000 brighter than V2 star

- Suppose \mathbf{E} is an unknown complex electric field. \mathbf{E} can be measured with 'probe' $p = Ae^{j\theta}$:

$$I = |\mathbf{E} + Ae^{j\theta}|^2$$

, where θ is $0, \pi/2, \pi, 3\pi/2$, and A is an arbitrary amplitude.

- Pair-wise estimation* is similar concept considering multiple pixels.

$$I_k^\pm = |\mathbf{E} \pm p_k|^2 \quad \rightarrow p_k \text{ are called "probes".}$$

- Probe equation:

$$\begin{pmatrix} I_1^+ - I_1^- \\ I_2^+ - I_2^- \end{pmatrix} = \begin{pmatrix} \text{Re}(p_1) & \text{Im}(p_1) \\ \text{Re}(p_2) & \text{Im}(p_2) \end{pmatrix} \begin{pmatrix} \text{Re}(\mathbf{E}) \\ \text{Im}(\mathbf{E}) \end{pmatrix}$$

Measurement

Probe amplitude ($|p_k|$) are measured.
Probe phase ($\angle p_k$) are model-based.

The probe amplitudes $|p_k|$ are independent to \mathbf{E} .

1st probe amplitude

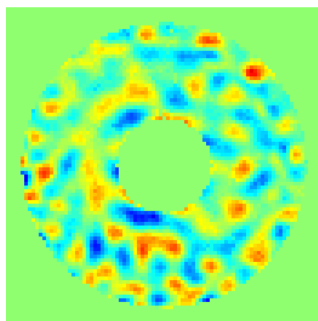
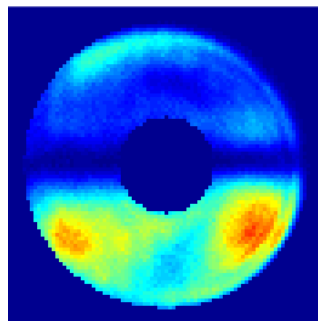
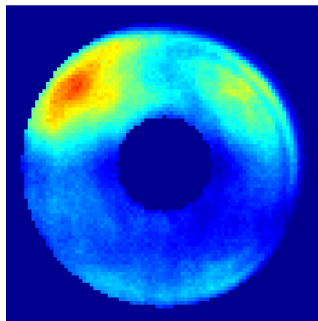
$$|p_1| = \sqrt{\frac{I_1^+ + I_1^-}{2}} - I_o$$

2nd probe amplitude

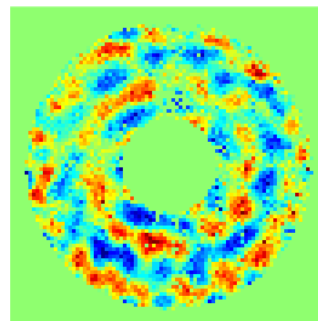
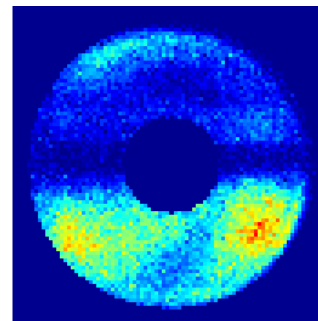
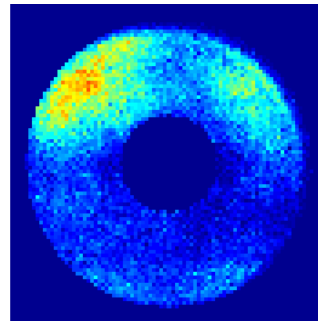
$$|p_2| = \sqrt{\frac{I_2^+ + I_2^-}{2}} - I_o$$

Estimated E_R

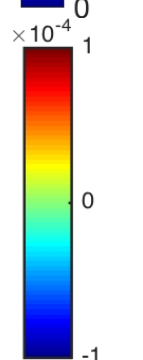
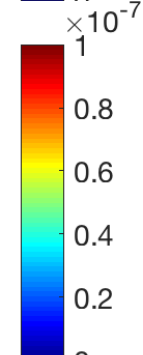
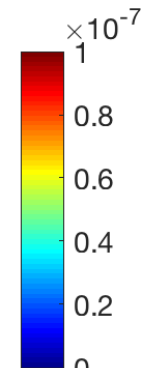
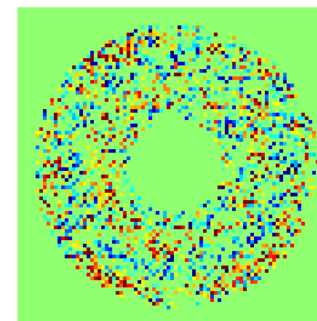
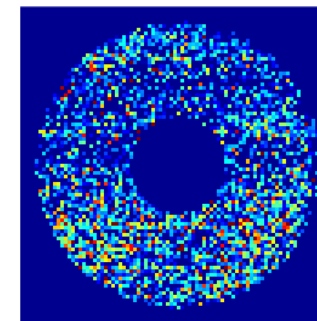
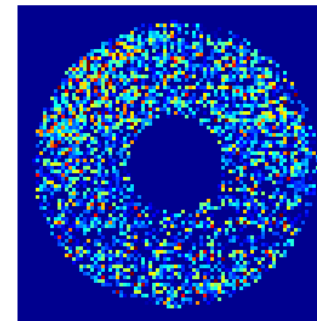
($t_{TB} = 5$ sec)
 $t_{flight} = 10K$ sec

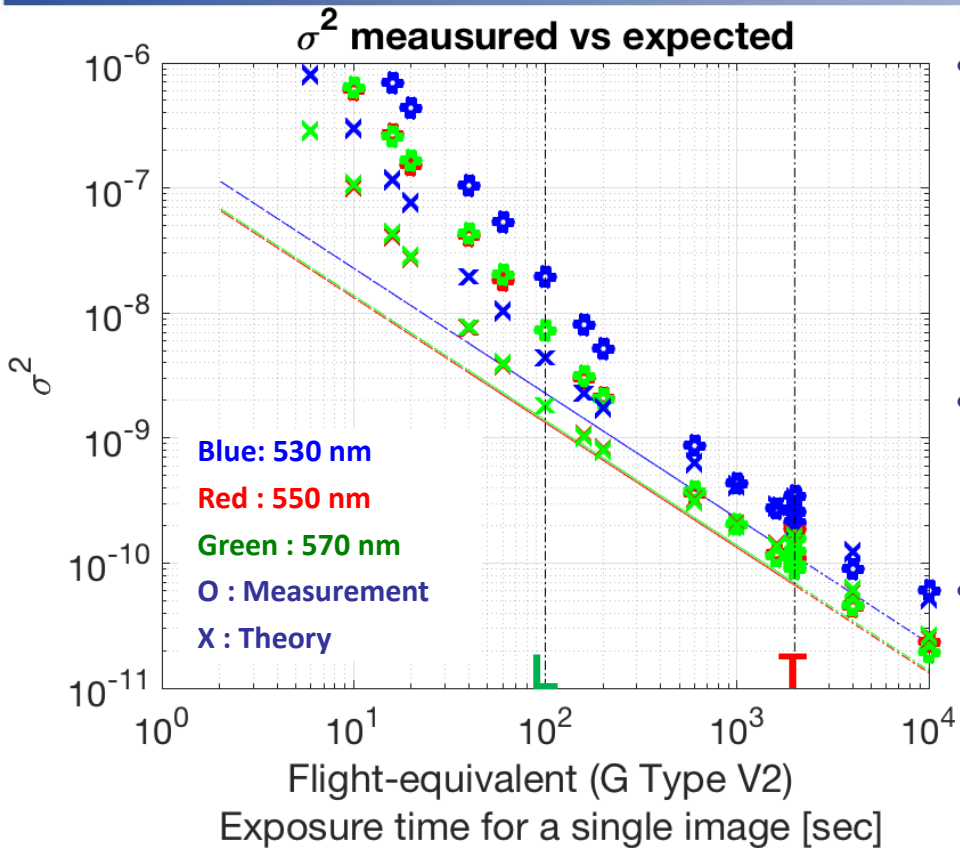


($t_{TB} = 0.5$ sec)
 $t_{flight} = 1000$ sec



($t_{TB} = 0.05$ sec)
 $t_{flight} = 100$ sec





T : Typical Testbed exposure time
L : Low flux environment (G-Type V2)

- E-field estimation uncertainty* (σ^2) is measured and compared to its expected value assuming the shot noise is dominant.

$$\sigma^2 = \langle \sigma^2(E_R) + \sigma^2(E_I) \rangle$$

, where $\sigma^2(E_{R/I})$ is variance of measured real/ imaginary

- For measured (O), we captured “repeatability” of E-Field uncertainty measurement.
- The expected values (X) assumes that the shot noise is dominant based on probing equation. Recall the equation below.

$$\begin{pmatrix} I_1^+ - I_1^- \\ I_2^+ - I_2^- \end{pmatrix} = \begin{pmatrix} Re(p_1) & Im(p_1) \\ Re(p_2) & Im(p_2) \end{pmatrix} \begin{pmatrix} Re(E) \\ Im(E) \end{pmatrix}$$

- The measurement includes ‘Read/Dark current’ noise of the CMOS detector. Their contribution will be negligible in flight due to EMCCD. Therefore, we are over-estimating the environment.

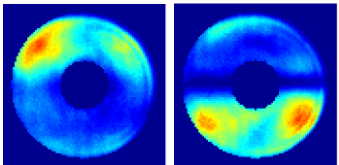
- Fail to achieve the success criteria in the first attempt mostly due to E-field estimation errors.
- Improved E-field estimation accuracy by **Probe Amplitude Look-Up-Table** : We use a specific probe *pattern* and *strength* and save their measured amplitudes.
- For flight, **Probe Amplitude Look-Up-Table** may be generated in GSE. (TBD)

Recall the probe equation.

$$\begin{pmatrix} I_1^+ - I_1^- \\ I_2^+ - I_2^- \end{pmatrix} = \begin{pmatrix} \text{Re}(p_1) & \text{Im}(p_1) \\ \text{Re}(p_2) & \text{Im}(p_2) \end{pmatrix} \begin{pmatrix} \text{Re}(\mathbf{E}) \\ \text{Im}(\mathbf{E}) \end{pmatrix}$$



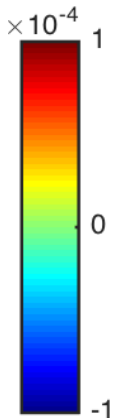
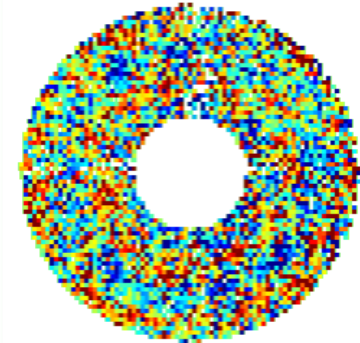
Probe amplitude Look-Up-Table

$$|p_k| = \sqrt{\frac{I_k^+ + I_k^-}{2} - I_o}$$


E-field estimation
Without LUT



E-field estimation
With LUT



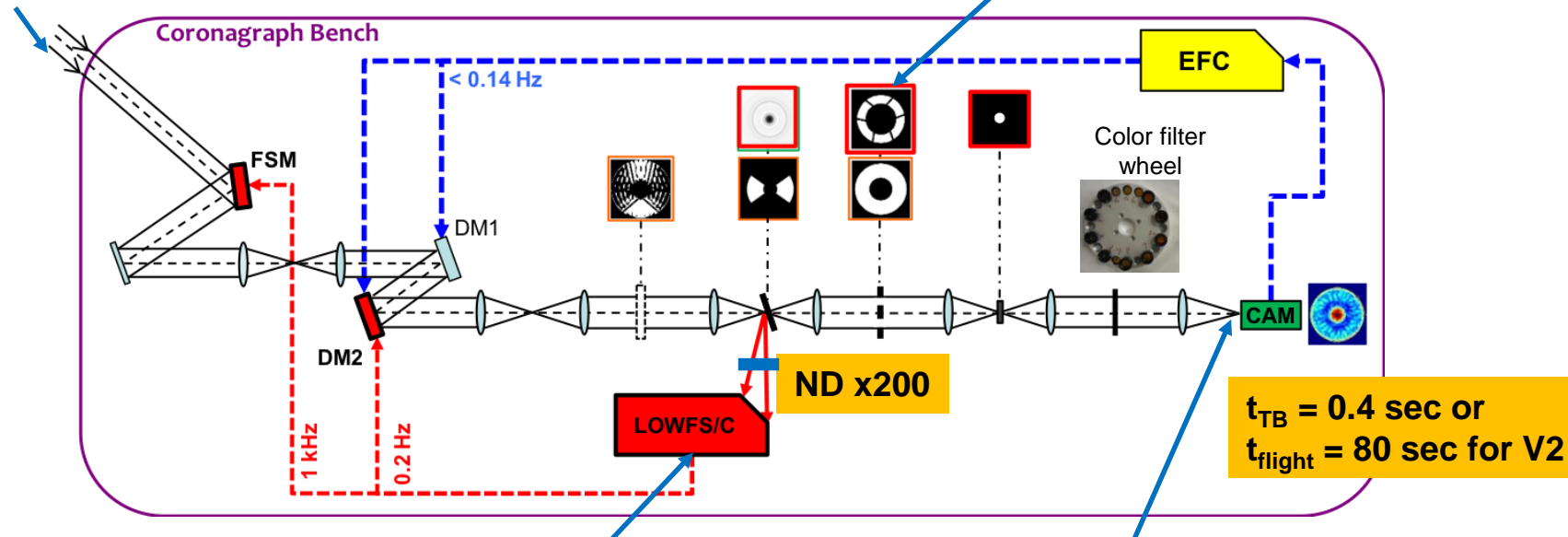
*We were able to measure E field
at $t_{\text{flight}} = 100 \text{ sec/V2}$ with LUT*

Star light

- 100 nm (18 %) Bandwidth @ 550 nm
- x 200 brighter than V2
- LoS jitter injected (~ 5 masRMS)
- Z4 drift injected (± 0.5 nm sinusoidal 30 min period)

Operation Mode

- Hybrid Lyot Coronagraph Mode
- HLC occulter, Lyotstop & fieldstop are selected.
- No SPC mask used.

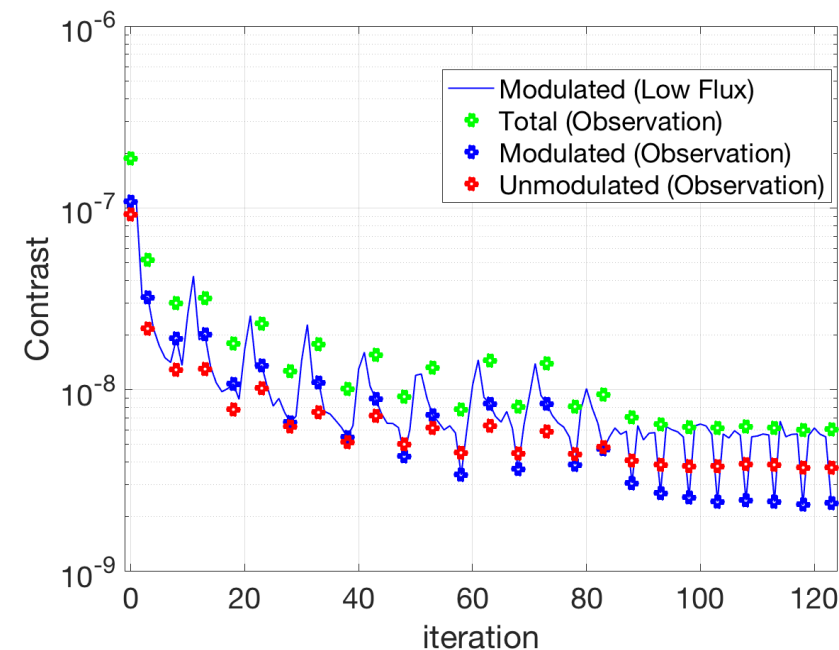


LOWFS

- Dim light using ND filter (x 1/200) for V2 operation
- LoS loop with refresh rate of 1 KHz
- DM loop (Z4) with refresh rate of 5 sec.

EFC

- Single image exposure of $t_{TB} = 0.4$ sec or $t_{flight} = 80$ sec for V2
- 3 channel (530 nm, 550 nm, 570 nm with 2%)

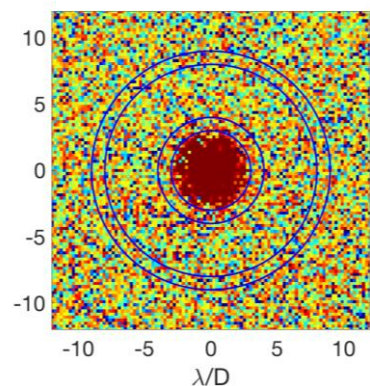


• Additional test setup

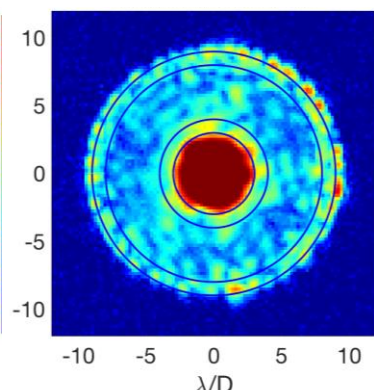
- Starting from an existing solution of $\sim 1\text{e-}7$.
- 3 band (530, 550, 570 nm) operation (baseline for WFIRST)
- Every 5 iteration is the observation cycle; Freeze DM and increase the exposure time for correct measurement.

Result: The final contrast meets the WFIRST raw contrast requirement.

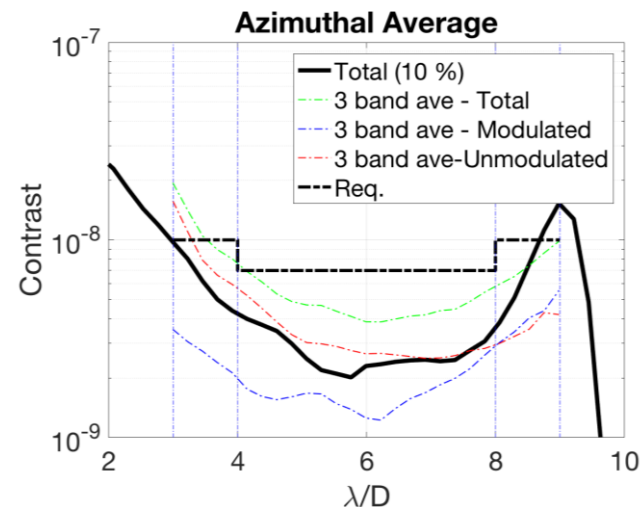
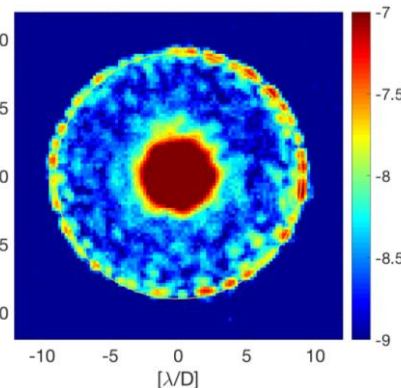
Iteration 123
@ $t_{\text{flight}}=80$ sec
Contrast N/A



Iteration 124 (Observing)
@ $t_{\text{flight}}=667$ min
Contrast $6.03\text{E-}9$ (3 band)



With 10% filter
@ $t_{\text{flight}}=\text{N/A}$
Contrast $4.86\text{E-}9$ (10%)





Dynamic Low Flux Test Testing items



- We test below...
 - LOWFS functions solid enough at V2 star for EFC to meet the success criteria in the flight equivalent flux.
 - E-Field estimation is accurate enough for EFC to to meet the success criteria in the flight equivalent flux.
 - The control loops work together without any conflict.
 - LOWFS functions solid enough at V5 star for EFC to meet the success criteria in the flight equivalent flux. (Discussed separately in 10698-94.)
- We DO NOT test below...
 - Superior EMCCD detector (We are overestimating).
 - LOWFS operation for Z5-Z11 (Astigmatism to Spherical).
 - Testbed drift. Instead of actually dimming the laser light, we make exposure to have the equivalent photon count, excluding any testbed drift issues.
 - We operate with three of 2 % bands with the 550 nm center wavelength (Hardware limitation). In flight, three 3.3% bands @575 nm will be used.
 - Use testbed star spectrum, which is different from the actual G-Type star spectrum (Flat @ 575 nm 10 %).



Summary & Future Works



- Summary
 - We have demonstrated generating a high contrast image in the WFIRST-like low flux dynamic environment.
- Next Steps in CY2019
 1. Update the OTA-Simulator
 - Simulate flight-like polarization
 - Increase perturbation DoF (Z5-Z11)
 2. Install a flight-like EMCCD
 3. Match flight λ filters (three 3.3% bands @575 nm)



Acknowledgement



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